SignLlava LUMI hackathon 2024

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Hackathon goals

- Optimization of our model based on Llama3
- Multi-node training
- Move to Llama-70b instead of Llama-8b
- Dealing with some existing problems
 - Correctly use flash-attention (1Torch was not compiled with flash attention)
 - Correctly use memory efficient attention (1Torch was not compiled with memory efficient attention)
 - SDPA attention implementation warnings for multi-node ROCM
- Moving our codes to latest Llama3.1 version

Dealing with some existing problems

- Correctly use flash-attention (1Torch was not compiled with flash attention)
- Correctly use memory efficient attention (1Torch was not compiled with memory efficient attention)
- Slow model loading

• Solved with new singularity image rocm6.1.3 + venv



Profiling of our model based on Llama3 8B

- Tools: rocprof v1 , omnitrace, torch.profiler
- Estabilished workflow setup
- Better understanding of the execution

• **Possible improvement:** Refactor of dataloader



Load balancing issue



Using Llama-70b instead of Llama-8b

- Successfully training with both 1-node and multi-node setups
- ZeRO3 parallelism
- Core parameter: stage3_prefetch_bucket_size
- Found bug in official release accelerate==1.0.1



Multi-node training

- Successfully training without deepspeed launcher
 - Llama3-8B
 - Llama3-70B
- Deepspeed launcher doesn't work yet
- A lot of sanity-check experiments
 - Weak spots in our code
 - Batch size and prefetch-bucket-size importance
- Not profiled yet



Moving to latest Llama3.1 version



What is left to do

- Improve our dataloader for GPU workload balance
- Profile the 70B model
- Profile multiple nodes
- Estimate scalability and best setup for our use-case

Highlights of this week

- New singularity image
- Discovery of load balance issue
- Llama3-70B model training
- Multi-node setups

